Binary choice	Structural estimation methods	Multinomial models	Application 1	Application 2	More examp
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Lecture 5. Nonlinear regression models

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Binary choice

- If Y_i is binary then $E(Y_i | X_i = x) = Pr(Y_i = 1 | X = x)$
 - the CEF is likely not linear
 - but OLS provides the best linear approximation to the CEF, *Pr*(Y_i = 1 | X_i)

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Binary choice

- Suppose *D_i* is a randomly assigned binary treatment variable.
 - let β^{OLS} denote the OLS estimand from a regression of Y_i on D_i
 - then

$$\beta^{OLS} = E(Y_i \mid D_i = 1) - E(Y_i \mid D_i = 0) = ATE$$

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Binary choice

• Suppose that $(Y_{1i}, Y_{0i}) \perp D_i \mid X_i$

• if the model is fully saturated in X_i,

$$\beta^{OLS} = \sum_{x} \delta_{x} w_{x}$$

where

• w_x are weights proportional to $P(x)(1 - P(x))Pr(X_i = x)$

•
$$\delta_x = E(Y_1 - Y_0 \mid X_i = x)$$

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AP's reasons to avoid probit/logit

- "regression gives us what we need with or without the probit distributional assumptions"
- "if the CEF has a causal interpretation, it seems fair to say that regression has a causal interpretation as well, because it still provides the MMSE approximation to the CEF"
- "...while a nonlinear model may fit the CEF ... more closely than a linear model, when it comes to marginal effects, this probably matters little."
- too many decisions to make along the way, while OLS is standardized
- life gets more complicated with IV and panel data

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Latent index model

Let Y^{*}_i = β'X_i + ε_i denote a latent index and suppose that we observe Y_i = 1(Y^{*}_i ≥ 0).

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Latent index model

- Let Y^{*}_i = β'X_i + ε_i denote a latent index and suppose that we observe Y_i = 1(Y^{*}_i ≥ 0).
 - back to generic notation where X_i can include a "treatment" and "controls"

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Latent index model

- Let Y^{*}_i = β'X_i + ε_i denote a latent index and suppose that we observe Y_i = 1(Y^{*}_i ≥ 0).
 - back to generic notation where X_i can include a "treatment" and "controls"
- If ε_i and X_i are independent then

$$Pr(Y_i = 1 | X_i) = F_{\varepsilon_i}(\beta' X_i)$$

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Latent index model

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- If ε_i and X_i are independent then

$$Pr(Y_i = 1 | X_i) = F_{\varepsilon_i}(\beta' X_i)$$

- if F_{ε_i} is the standard normal cdf this is the *probit* model
- if $F_{\varepsilon_i}(x) = \frac{\exp(x)}{1 + \exp(x)}$ this is the *logit* model
- if $F_{\varepsilon_i}(x) = x \mathbf{1}(0 \le x \le 1)$ this is the linear probability model

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Latent index model

- The latent index may have a structural interpretation (random utility, shadow price, etc.).
- In the structural interpretation it often does not make sense to restrict the standard deviation of ε_i.
 - Assume that ε_i | X_i ∼ N(0, σ_ε²)

Then

$$egin{aligned} &Y_i = \mathbf{1}(eta' X_i + arepsilon_i \geq \mathbf{0}) \ &= \mathbf{1}(rac{eta}{\sigma_arepsilon}' X_i + rac{arepsilon_i}{\sigma_arepsilon} \geq \mathbf{0}) \end{aligned}$$

• Thus
$$Pr(Y_i = 1 | X_i) = \Phi\left(\frac{\beta'}{\sigma_{\varepsilon}}X_i\right)$$

Binary choice Str

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Latent index model

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 - Assume that ε_i | X_i ∼ N(0, σ_ε²)

• Then

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- Thus $Pr(Y_i = 1 | X_i) = \Phi\left(\frac{\beta'}{\sigma_{\varepsilon}}X_i\right)$
- so we can't separate β from σ_{ε}

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Marginal effects

- marginal effect of a continuous regressor: $\frac{\partial}{\partial x_k} Pr(Y_i = 1 \mid X_i = x) = \beta_k f_{\varepsilon_i}(\beta' x)$
- the partial effect of a discrete regressor
 - Suppose $X_i = (D_i, \tilde{X}_i)$.
 - We estimate the partial effect of D_i as a difference: $F_{\varepsilon_i}(\beta_0 + \beta_1 + \beta'_2 \tilde{x}) - F_{\varepsilon_i}(\beta_0 + \beta'_2 \tilde{x})$
- marginal effects at the mean: $\beta_k f_{\varepsilon_i}(\beta' \bar{X})$
- average marginal effect: $\beta_k E(f_{\varepsilon_i}(\beta'X_i))$
- margins command in Stata



Estimation

• estimation is via maximum likelihood:

$$\hat{\beta} = \max_{\beta} \sum_{i=1} Y_i ln \left(F_{\varepsilon}(\beta' X_i) \right) + (1 - Y_i) ln \left(1 - F_{\varepsilon}(\beta' X_i) \right)$$

• in small samples or high dimensional models you might experience convergence problems:



Estimation

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- in small samples or high dimensional models you might experience convergence problems:
 - the MLE does not exist if there is a β such that β'X_i ≥ 0 for all i : Y_i = 0 and β'X_i ≤ 0 for all i : Y_i = 1
 - it is not clear whether Stata is able to catch all cases of this
 - if the "overlap" is small and there are many regressors then Stata's algorithm my have difficulty converging
 - problems with approximating probit cdf when probabilites are close to 0/1 (outliers)

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probit/logit versus OLS

causal effects in the latent index model:

• independence between ε_i and (D_i, X_i) implies CIA

then

$$\delta_x = E(Y_{1i} - Y_{0i} | X_i = x)$$

= $F_{\varepsilon_i}(\beta_0 + \beta_1 + \beta'_2 x) - F_{\varepsilon_i}(\beta_0 + \beta'_2 x)$

- nonlinearity induces heterogeneous effects
- if the model is not fully saturated in *X_i*, the nonlinearity can make problems even worse

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probit/logit versus OLS

• causal effects in the latent index model:

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- nonlinearity induces heterogeneous effects
- if the model is not fully saturated in *X_i*, the nonlinearity can make problems even worse
- misspecification is a valid concern
 - suppose ε_i is heteroskedastic
 - one solution to this problem is a semiparametric model (average derivative methods or maximum score methods)

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Illustration of OLS bias

• I simulated the following model:

$$egin{aligned} X_i &\sim N(0,1) \ D_i &= \mathbf{1}(\gamma_0 + X_i \geq v_i), \quad v_i \sim N(0,1) \ Y_i &= \mathbf{1}(0.5D_i + X_i \geq u_i), \quad u_i \sim N(0,1) \end{aligned}$$

- The ATE is $E(\Phi(.5 + X_i) \Phi(X_i)) \approx 0.14$
- I simulate the model for a grid of values of γ_0 between -3 and 3 for n = 1000 observations.

Structural estimation method:

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Illustration of OLS bias



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Structural models

- Over the next few lectures I want to introduce you to structural estimation methods.
- Today I begin by familiarizing you with some nonlinear models which are commonly used.
- We will also take about maximum likelihood because this gives us practice in moving from an economic model to an econometric specification.
- Next class we will discuss other estimation methods.

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Maximum likelihood

- You've seen theoretical conditions for maximum likelihood estimation before. See Cameron and Trivedi for a review.
- Suppose we observe a vector of outcomes *Y_i* and covariates *X_i*.
- Our model fully specifies, up to a parameter vector β, the distribution of Y_i conditional on X_i via a density f_{Y|X}(Y_i | X_i; β).

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Maximum likelihood

• With iid data, the likelihood function is

$$L(\beta) = \prod_{i=1}^{n} f_{Y|X}(Y_i \mid X_i; \beta)$$

• Let $\mathcal{L}(\beta) = log(\mathcal{L}(\beta)) = \sum_{i=1}^{n} log(f_{Y|X}(Y_i \mid X_i; \beta))$. Then

$$\hat{eta}_{\textit{MLE}} = \mathop{\textit{arg}}\limits_{eta} \max_{eta} \mathcal{L}(eta)$$

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Properties of MLE

•
$$\hat{\beta}_{MLE} \rightarrow_{p} \beta$$
 and $\sqrt{n}(\hat{\beta}_{MLE} - \beta) \rightarrow_{d} N(0, \mathcal{I}^{-1})$ where

• $\mathcal{I} = plim_{n \to \infty} \frac{1}{N} \frac{\partial \mathcal{L}(\beta)}{\partial \beta} \frac{\partial \mathcal{L}(\beta)}{\partial \beta'}$ (Fisher information matrix)

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Properties of MLE

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$$\hat{\beta}_{MLE} \rightarrow_{p} \beta$$
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• $\mathcal{I} = plim_{n \rightarrow \infty} \frac{1}{N} \frac{\partial \mathcal{L}(\beta)}{\partial \beta} \frac{\partial \mathcal{L}(\beta)}{\partial \beta'}$ (Fisher information matrix)
• $E\left(\frac{\partial \mathcal{L}(\beta)}{\partial \beta} \frac{\partial \mathcal{L}(\beta)}{\partial \beta'}\right) = -E\left(\frac{\partial^{2} \mathcal{L}(\beta)}{\partial \beta \partial \beta'}\right)$ (information matrix equality)

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Properties of QMLE

- Suppose $f_{Y|X}(Y_i | X_i; \beta)$ is not the correct density.
 - $\hat{\beta}_{MLE} \rightarrow_{p} \beta^{*}$, pseudo-true value that maximizes $plim_{n \rightarrow \infty} \frac{1}{n} \mathcal{L}(\beta)$

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Properties of QMLE

- Suppose $f_{Y|X}(Y_i | X_i; \beta)$ is not the correct density.
 - $\hat{\beta}_{MLE} \rightarrow_{p} \beta^{*}$, pseudo-true value that maximizes $plim_{n \rightarrow \infty} \frac{1}{n} \mathcal{L}(\beta)$
 - $\sqrt{n}(\hat{\beta}_{MLE} \beta^*) \rightarrow_d N(0, A^{-1}BA^{-1})$ where
 - $B = plim_{n \to \infty} \frac{1}{N} \frac{\partial \mathcal{L}(\beta)}{\partial \beta} \frac{\partial \mathcal{L}(\beta)}{\partial \beta'}$ and $A = plim_{n \to \infty} \frac{1}{N} \frac{\partial^2 \mathcal{L}(\beta)}{\partial \beta \partial \beta'}$

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Properties of (Q)MLE

- Under correct specification, $A^{-1}BA^{-1} = B^{-1} = \mathcal{I}^{-1}$.
- Example:
 - OLS is equivalent to MLE assuming homoskedastic normal errors
 - If errors are heteroskedastic, we can use a sandwich formula that accounts for heteroskedasticity (Eicker-Huber-White standard errors)
 - In this case, the pseudo-true value is β .
 - The "robust" option for a probit does the same thing, but the pseudo-true value is not β

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Nonlinear least squares

- The nonlinear least squares (NLS) estimator is an alternative to MLE.
 - less efficient than MLE
 - but relies on weaker distributional assumptions

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Nonlinear least squares

- The nonlinear least squares (NLS) estimator is an alternative to MLE.
 - less efficient than MLE
 - but relies on weaker distributional assumptions
- Suppose $Y_i = g(X_i, \beta) + u_i$ and $E(u_i \mid X_i) = 0$.
- Then $\hat{\beta}_{NLS}$ minimizes

$$\sum_{i=1}^n (Y_i - g(X_i, \beta))^2$$

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Nonlinear least squares

- Sandwich variance matrix:
 - $\hat{\beta}_{NLS} \rightarrow_p \beta$ and $\sqrt{n}(\hat{\beta}_{NLS} \beta) \rightarrow_d N(0, A^{-1}BA^{-1})$
 - where $A = plim_{n \to \infty} \frac{1}{n} \sum_{i=1}^{n} \frac{\partial g(X_{i,\beta})}{\partial \beta} \frac{\partial g(X_{i,\beta})}{\partial \beta'}$ and $B = plim_{n \to \infty} \frac{1}{n} \sum_{i=1}^{n} \sum_{j=1}^{n} E(u_{i}u_{j} \mid X) \frac{\partial g(X_{i,\beta})}{\partial \beta} \frac{\partial g(X_{i,\beta})}{\partial \beta'}$

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Other estimators

- Variations on NLS (e.g., FGNLS)
- GMM (more on this in a few classes)
- simulation-based versions of these

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Random utility model for multinomial outcomes

We can start with a very general random utility model.

- Individual (or household, firm, etc.) *i* has a choice among *m* alternatives.
- For *j* = 1,..., *m*, utility for choice *j* is U_{ij} = V_{ij} + ε_{ij} where V_{ij} will be a function of observables and ε_{ij} is unobservable.
- Then the probability that *i* chooses *j* (conditional on observables) is:

$$egin{aligned} \mathcal{P}_{ij} &:= \mathcal{P}r\left(\mathcal{U}_{ij} = \max_{k=1,...,m} \mathcal{U}_{ik}
ight) \ &= \mathcal{P}r\left(arepsilon_{ik} - arepsilon_{ij} \leq \mathcal{V}_{ij} - \mathcal{V}_{ik} ext{ for all } k
eq j
ight) \end{aligned}$$

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Random utility model for multinomial outcomes

- The log likelihood is then $\sum_{i=1}^{n} \sum_{j=1}^{m} \log(p_{ij})y_{ij}$ where y_{ij} is equal to 1 if observation *i* chose option *j* and 0 otherwise.
- There are then two choices to make:
 - how to specify V_{i1}, \ldots, V_{im}
 - how to specify the joint distribution of $\varepsilon_{i1}, \ldots, \varepsilon_{im}$

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Multinomial logit model

- Logit models are derived from the assumption that $\varepsilon_{i1}, \ldots, \varepsilon_{im}$ are independent with identical type 1 extreme value distributions
 - sometimes called the Gumbel distribution, sometimes abbreviated EV1, this distribution has cdf $F(x) = e^{-e^{-x}}$
- Under this assumption,

$$\rho_{ij} = \frac{\exp(V_{ij})}{\sum_{k=1}^{m} \exp(V_{ij})} \\
= \frac{\exp(V_{ij} - V_{i1})}{1 + \sum_{k=2}^{m} \exp(V_{ij} - V_{i1})}$$

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Multinomial logit model

Independence of irrelevant alternatives (IIA)

• Notice that for two choices $j \neq k$,

$$\frac{p_{ij}}{p_{ik}} = \frac{\exp(V_{ij})}{\exp(V_{ik})}$$

- The relative probability of the two options is not affected by other options at all!
- "red bus-blue bus" problem

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Multinomial logit model

Specifying Vij

- What makes utility of one choice higher than utility of another?
 - choice-specific characteristics, including price
 - preferences, which vary with individual characteristics
- A general model that includes both: $V_{ij} = \beta' x_{ij} + \gamma'_i w_i$
 - *x_{ij}* are choice-specific characteristics, which may also vary with the individual
 - *w_i* is an individual characteristic and *γ_j* reflects how this characteristic influence utility of choice *j*
 - note that we must normalize $\gamma_1 = 0$

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Multinomial logit model

Specifying V_{ij}

- note that $V_{ij} V_{i1} = \beta'(x_{ij} x_{i1}) + (\gamma_j \gamma_1)' w_i$
- we can always add the same constant to γ_j and γ₁ and the likelihood does not change

• so we must normalize $\gamma_1 = 0$

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Multinomial logit model

Marginal effects

• For the choice-specific variables:

$$rac{\partial oldsymbol{
ho}_{ij}}{\partial x_{ij}} = oldsymbol{
ho}_{ij} (1 - oldsymbol{
ho}_{ij})eta \ rac{\partial oldsymbol{
ho}_{ij}}{\partial x_{ik}} = -oldsymbol{
ho}_{ij}oldsymbol{
ho}_{ik}eta, k
eq j$$

• For regressors that don't vary with choice:

$$\frac{\partial \boldsymbol{p}_{ij}}{\partial \boldsymbol{w}_i} = \boldsymbol{p}_{ij} \left(\gamma_j - \sum_{k=1}^m \gamma_k \boldsymbol{p}_{ik} \right)$$

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Multinomial logit model

Log odds ratio interpretation

• If
$$V_{ij} = \gamma'_j w_i$$
 then

$$\log\left(\frac{\rho_{ij}}{\rho_{ik}}\right) = (\gamma_j - \gamma_k)' w_i$$

 Since γ₁ = 0, coefficient estimates γ̂_j can then be interpreted as the increase in the log odds ratio of choice j relative to choice 1 due to a one unit increase in w_i.

Alternatively, we can simulate the model to answer different policy counterfactuals.

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Multinomial logit model

In Stata

- mlogit
 - data structure each row is an individual and the depvar is a categorical variable
 - syntax mlogit depvar indepvars, baseoutcome (value) where value is the value for the dependent variable indicating the choice where we impose the normalization
 - model only works for $V_{ij} = \gamma'_j w_i$
- asclogit
 - data structure each row is an individual, choice pair and the depvar is a dummy variable
 - syntax asclogit depvar indepvars, case(id) alternatives(choice) basealternative(value) where value is the value for the dependent variable indicating the choice where we impose the normalization.
 - model works for $V_{ij} = \beta' x_{ij} + \gamma'_j w_i$
 - wi are specified using casevars option

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Multinomial logit model

More on IIA

- Suppose $V_{ij} = \alpha \cdot price_j + \beta' x_{ij} + \gamma'_j w_i$.
- Then the cross price elasticity $\left(\frac{\partial p_{ij}}{\partial price_k}\frac{price_k}{p_{ij}}\right)$ is equal to

$\alpha price_k p_{ik}$.

- It is the same for all *j*!!
- One solution is to model the correlations between ε_{ij} and ε_{ik} explicitly (see multinomial probit next class).
- Two more solutions will be previewed.

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Nested logit model

- In some cases we can group choices together red bus and blue bus are both buses.
- The nested logit models the probability of choosing option *k* which is part of group *j* by

$$p_{jk} = p_j \times p_{k|j}$$

 For the nested logit with V_{jk} = α'z_j + β'x_{jk} for J groups where group j has K_j choices:

$$p_{jk} = \frac{\exp(\alpha' z_j + \rho_j I_j)}{\sum_{m=1}^{J} \exp(\alpha' z_j + \rho_j I_j)} \frac{\exp\left((\beta_j / \rho_j)' x_{jk}\right)}{\sum_{l=1}^{K_j} \exp\left((\beta_j / \rho_j)' x_{jl}\right)}$$

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Random coefficients logit model

- We can generalize the utility model to include an individual-specific coefficient that is treated as a "random effect" V_{ij} = β'_ix_{ij}.
- In this model,

$$p_{ij} = \int p_{ij}(eta_i) f_{eta_i}(eta_i) deta_i$$

where $p_{ij}(\beta) = \frac{\exp(\beta' x_{ij})}{\sum_{k=1}^{m} \exp(\beta' x_{ik})}$

• Typically f_{β_i} is specified as a normal distribution with a mean and variance to be estimated.

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Kleven et al. (2013)

- A model for country choice (of European football players).
 - The multinomial choice model: for player *i* in time *t* playing in country *n* yields utility:

$$U_{nt}^{i} = \alpha log(1 - \tau_{nt}^{i}) + \alpha log(w_{nt}^{i}) + home_{n}^{i} + x_{t}^{i}\beta_{n} + \gamma_{n} + \nu_{nt}^{i}$$

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Kleven et al. (2013)

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$$U_{nt}^{i} = \alpha log(1 - \tau_{nt}^{i}) + \alpha log(w_{nt}^{i}) + home_{n}^{i} + x_{t}^{i}\beta_{n} + \gamma_{n} + \nu_{nt}^{i}$$

- multinomial logit
- can you map the notation here to the general notation for the multinomial logit above in the slides?
- various specifications to account for not observing wⁱ_{nt}
- probability that *i* chooses *n* in year *t* is $P_{nt}^{i} = Pr(U_{nt}^{i} \ge U_{mt}^{i} \quad \forall m)$

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Kleven et al. (2013)

- Tax elasticities:
 - they compare estimates of

$$\varepsilon_{domestic}^{n} = \frac{d \log(\sum_{i \in I_n} P_{nt}^{i})}{d \log(1 - \tau_{nd})} = \alpha (1 - \bar{P}_{n}^{d})$$

and

$$\varepsilon_{\textit{foreign}}^{n} = \frac{d \log(\sum_{i \in I_{n}^{C}} P_{nt}^{i})}{d \log(1 - \tau_{nf})} = \alpha (1 - \bar{P}_{n}^{f})$$

 these formulas show how restrictive the multinomial logit can be

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Christensen and Kiefer

A job search model

- Suppose job offers are distributed according to a density f(w).
- There is a reservation wage w_r such that each worker i accepts offer w_i if w_i ≥ w_r.
- The distribution of accepted offers is

$$g(w) = \frac{f(w)}{\int_{w_r}^{\infty} f(w) dw} \mathbf{1}(w \ge w_r)$$

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Christensen and Kiefer

Taking the model to data

- Suppose f(w) and w_r are parameterized by a vector θ .
- We observe a sample of wages for workers (who are assumed to have accepted a wage offer).
- So we observe (w_1, \ldots, w_n) , an iid sample from g(w).
- Thus, the likelihood is

$$L(\theta) = \prod_{i=1}^{n} \frac{f(w_i; \theta)}{\int_{w_r(\theta)}^{\infty} f(w; \theta) dw} \mathbf{1}(w_i \ge w_r(\theta))$$

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Christensen and Kiefer

Taking the model to data

- One option is to take $f(w) = \gamma \exp(-\gamma(w c))$.
- It turns out that *g* does not end up depending on *c* so we can take $\theta = (\gamma, w_r)$ and

$$L(\theta) = \gamma^n \exp\left(-\gamma \sum_{i=1}^n (w_i - w_r)\right) \mathbf{1}(\min(w_i) \ge w_r)$$

• This likelihood function has some weird properties (regardless of how *f*(*w*) is parameterized; assumption (iv) in Prop 5.5 in CT; see the paper for details) so the authors assume wages are observed with error.

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Christensen and Kiefer

Model with measurement error

- It is assumed that we observe $w_i^e = w_i m_i$ where w_i is iid from g(w).
- They maintain the shifted exponential assumption, $f(w) = \gamma \exp(-\gamma(w - c)).$
- The measurement error, m_i is assumed to have density $h(m_i)$ with support on $[0, \infty)$.
- Note then that for any *x*,

$$Pr(w_i^e \leq x) = \int_0^\infty Pr(w_i \leq \frac{x}{m_i} \mid m_i)h(m_i)dm_i$$

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Christensen and Kiefer

Model with measurement error

This can be written as

$$Pr(w_i^e \leq x) = \int_0^{x/w_r} \left(1 - \exp(-\gamma(x/m_i - w_r))\right) h(m_i) dm_i$$

To derive the likelihood function we need the density of w^e_i, which will be denoted f_e(x).

$$f_{e}(x) = \frac{d}{dx} Pr(w_{i}^{e} \le x)$$
$$= \gamma \exp(\gamma w_{r}) \int_{0}^{x/w_{r}} \frac{1}{m} h(m) \exp(-\gamma x/m) dm$$

• This is derived assuming certain properties of *h*.

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More examples

Christensen and Kiefer

Specifying the distribution of measurement error

- First, the density *h* must satisfy some properties for *f_e* to take the form on the previous slide.
- Second, we want to use a flexible family of distributions as we do not know much about what the distribution should look like.
- Further, we want the resulting expression for *f_e* to be tractable.

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More examples

Christensen and Kiefer



FIG. 1.-Observed wage densities

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Likelihood function

- Moving from a model, written in equations, to the appropriate likelihood function?
- Can be difficult if your model isn't a textbook case.
- Here I will provide some examples.

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More examples

- Let *Y*^{*} denote the outcome of interest.
- (Right-) censoring occurs when we observe $Y = Y^*$ if $Y^* \leq C$ and we observe Y = C for the individuals with $Y^* > C$.
- We will consider both the case where *C* varies across individuals and the case where it is a constant.



Truncation

- Let *Y*^{*} denote the outcome of interest.
- Truncation occurs when we observe Y = Y* if Y* ≤ C and we don't observe the individuals with Y* > C at all (as in the Christensen and Kiefer model).
- Again, C may or may not vary across individuals.



Application 2

More examples

- Consider a sample of durations (y_1, \ldots, y_n) and covariates (x_1, \ldots, x_n) .
- Suppose the conditional density for Y* is given by f(y | x, θ).
- If $y_i = y_i^*$ for all *i* then the likelihood is simply $\mathcal{L}(\theta) = \sum_{i=1}^n \log(f(y_i \mid x_i, \theta)).$
- What if some observations are censored?

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More examples

- Non-random censoring:
 - The likelihood should be the distribution of what we observe.
 - Here we observe both Y_i and $D_i = \mathbf{1}(Y_i^* \leq C)$.

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More examples

- Non-random censoring:
 - The likelihood should be the distribution of what we observe.
 - Here we observe both Y_i and $D_i = \mathbf{1}(Y_i^* \leq C)$.
 - If $d_i = 1$ then $Pr(Y_i = y_i, D_i = d_i | X_i) = Pr(Y_i^* = y_i, Y_i^* \le C | X_i) = Pr(Y_i^* = y_i | X_i).$
 - If $d_i = 0$ then $y_i = C$ and $Pr(Y_i = y_i, D_i = d_i | X_i) = Pr(Y_i^* > C | X_i).$

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- Non-random censoring:
 - The likelihood should be the distribution of what we observe.
 - Here we observe both Y_i and $D_i = \mathbf{1}(Y_i^* \leq C)$.
 - If $d_i = 1$ then $Pr(Y_i = y_i, D_i = d_i | X_i) = Pr(Y_i^* = y_i, Y_i^* \le C | X_i) = Pr(Y_i^* = y_i | X_i).$
 - If $d_i = 0$ then $y_i = C$ and $Pr(Y_i = y_i, D_i = d_i | X_i) = Pr(Y_i^* > C | X_i).$
 - So the log-likelihood is given by

$$\sum_{i=1}^{n} D_i \ln(f(y_i \mid x_i, \theta)) + (1 - D_i) \ln\left(\int_{C}^{\infty} f(y \mid x_i, \theta) dy\right)$$

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More examples

- Random censoring:
 - Suppose censoring times are random, C_i , with distribution $f_{C|X}(c \mid x, \theta)$.
 - Assume that Y_i^* and C_i are independent conditional on X_i .

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More examples

- Random censoring:
 - Suppose censoring times are random, C_i , with distribution $f_{C|X}(c \mid x, \theta)$.
 - Assume that Y_i^* and C_i are independent conditional on X_i .
 - If *d_i* = 1 then

$$\begin{aligned} \mathsf{Pr}(\mathsf{Y}_i = \mathsf{y}_i, \mathsf{D}_i = \mathsf{d}_i \mid \mathsf{X}_i) &= \mathsf{Pr}(\mathsf{Y}_i^* = \mathsf{y}_i, \mathsf{Y}_i^* \leq \mathsf{C}_i \mid \mathsf{X}_i) \\ &= \mathsf{Pr}(\mathsf{Y}_i^* = \mathsf{y}_i, \mathsf{C}_i \geq \mathsf{y}_i \mid \mathsf{X}_i) \\ &= \mathsf{f}(\mathsf{y}_i \mid \mathsf{x}_i, \theta) \int_{\mathsf{y}_i}^{\infty} \mathsf{f}_{\mathsf{C}}(\mathsf{y} \mid \mathsf{x}_i, \theta) \mathsf{d}\mathsf{y} \end{aligned}$$

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More examples

Censoring

- Random censoring:
 - Suppose censoring times are random, C_i , with distribution $f_{C|X}(c \mid x, \theta)$.
 - Assume that Y_i^* and C_i are independent conditional on X_i .
 - If *d_i* = 1 then

$$\begin{aligned} \mathsf{Pr}(\mathsf{Y}_i = \mathsf{y}_i, \mathsf{D}_i = \mathsf{d}_i \mid \mathsf{X}_i) &= \mathsf{Pr}(\mathsf{Y}_i^* = \mathsf{y}_i, \mathsf{Y}_i^* \leq \mathsf{C}_i \mid \mathsf{X}_i) \\ &= \mathsf{Pr}(\mathsf{Y}_i^* = \mathsf{y}_i, \mathsf{C}_i \geq \mathsf{y}_i \mid \mathsf{X}_i) \\ &= f(\mathsf{y}_i \mid \mathsf{x}_i, \theta) \int_{\mathsf{y}_i}^{\infty} f_{\mathsf{C}}(\mathsf{y} \mid \mathsf{x}_i, \theta) d\mathsf{y} \end{aligned}$$

• If $d_i = 0$ then $y_i = C_i$ and

$$\begin{aligned} \Pr(Y_i = y_i, D_i = d_i \mid X_i) &= \Pr(C_i = y_i, Y_i^* > C_i \mid X_i) \\ &= f_C(y_i \mid x_i, \theta) \int_{y_i}^{\infty} f(y \mid x_i, \theta) dy \end{aligned}$$

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More examples

Truncation

- non-random censoring:
 - The likelihood should be the distribution of what we observe, *conditional on being observed*.
 - This is usually implicit.

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More examples

Truncation

- non-random censoring:
 - The likelihood should be the distribution of what we observe, *conditional on being observed*.
 - This is usually implicit.
 - Here,

$$Pr(Y_i = y_i \mid D_i = 1, x_i) = Pr(Y_i^* = y_i \mid Y_i^* \le C, x_i)$$
$$= \frac{Pr(Y_i^* = y_i, Y_i^* \le C \mid x_i)}{Pr(Y_i^* \le C \mid x_i)}$$
$$= \frac{f(y_i \mid x_i, \theta)}{\int_{-\infty}^{C} f(y \mid x_i, \theta) dy}$$

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More examples

Truncation

- non-random censoring:
 - The likelihood should be the distribution of what we observe, *conditional on being observed*.
 - This is usually implicit.
 - Here,

$$Pr(Y_{i} = y_{i} | D_{i} = 1, x_{i}) = Pr(Y_{i}^{*} = y_{i} | Y_{i}^{*} \leq C, x_{i})$$

$$= \frac{Pr(Y_{i}^{*} = y_{i}, Y_{i}^{*} \leq C | x_{i})}{Pr(Y_{i}^{*} \leq C | x_{i})}$$

$$= \frac{f(y_{i} | x_{i}, \theta)}{\int_{-\infty}^{C} f(y | x_{i}, \theta) dy}$$

• So the log-likelihood is

$$\sum_{i=1}^{n} \log(f(y_i \mid x_i, \theta)) - \log\left(\int_{-\infty}^{C} f(y \mid x_i, \theta) dy\right)$$

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More examples

Truncation

• random censoring:

Now we get

$$Pr(Y_{i} = y_{i} | D_{i} = 1, x_{i}) = Pr(Y_{i}^{*} = y_{i} | Y_{i}^{*} \leq C_{i}, x_{i})$$

$$= \frac{Pr(Y_{i} = y_{i}, Y_{i}^{*} \leq C_{i} | x_{i})}{Pr(Y_{i}^{*} \leq C_{i} | x_{i})}$$

$$= \frac{f(y_{i} | x_{i}, \theta)(1 - F_{C}(y_{i} | x_{i}, \theta))}{\int_{-\infty}^{\infty} f(y | x_{i}, \theta)(1 - F_{C}(y | x_{i}, \theta))dy}$$

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More examples

Identification

- An important part of structural modeling: determining model identification
 - Just because we can write down a likelihood function does not mean the model is identified.
 - Consider the random censoring model:
 - suppose we assume instead that $D_i = \mathbf{1}(Y_i^* \leq C_i + c_0)$
 - we can add a constant to *c*₀ and shift the density of *C_i* by the same constant without changing the likelihood function
 - so the model is not identified!
 - We will give some more examples of this next week.